

Diving Into the Organics Cart

A Residential Waste AI Technology Challenge

SWANA 2022 Canadian Symposium

April 6, 2022



Our Circular Food Economy

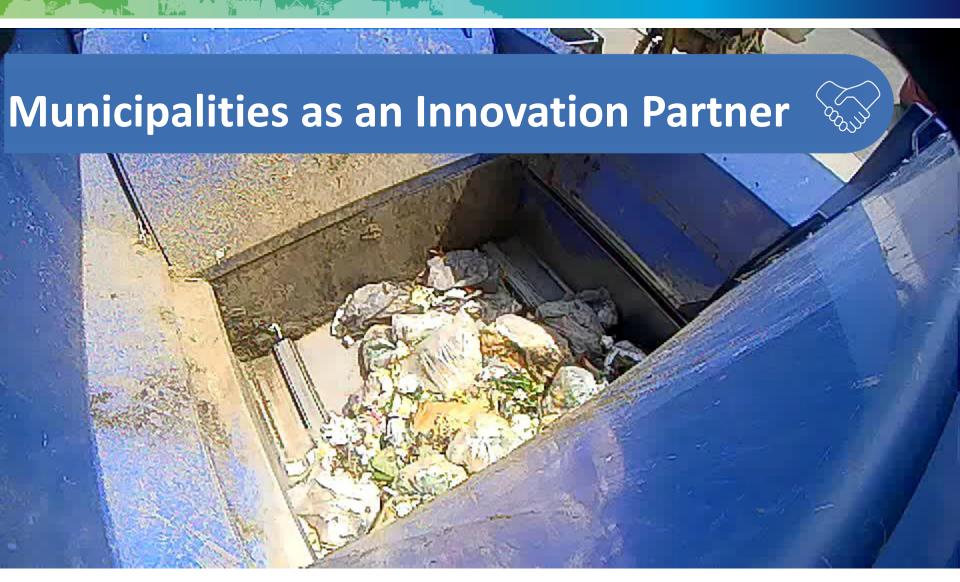




Guelph's Cart System









Challenge Specifics

- Challenge Statement
 - How might the City of Guelph consistently collect detailed household-level data on avoidable food loss/waste or incorrect sorting in the organics collection stream (green cart), that can be used to help households understand their own food waste and inform city-wise food waste reduction projects?
- Solution
- Applicability



Eagle Vision Systems





Initial Contaminant List

Contaminant Selection worksheet	Draft Priority
Please put in your ranking of the items. Acceptable Items - Transparent Bags	
- Pulp Cartons (Egg Cartons)	Acceptable
- Cut Flowers	Acceptable
- Small Brown Paper Bags	Acceptable Acceptable
- Peat Containers	·
Higher Priority Contaminants - Yard Waste/Soil	Acceptable
- Solid (Non-Transparent) Bags	2
- Food Waste (Meats, Fruits, Vegetables, Bread)	3
- Plastic Bags (Black, blue, any non-compostable bags, Large Transparent Bags)	4
- Large Brown Bags	5
- Recyclables (Plastics/Metals)(Containers, Cans, Bottles, etc.)	6
Lower Priority Contaminants - Animal Waste Bags	7
- Plates (Plastic and paper plates) ALL PLASTICITEMS Higher Priority	8
- Wood	9
- Paper (Loose Papers)	10
- Cardboard (Pizza boxes, etc.)	11
- Plastic Trays ALL PLASTICITEMS Higher Priority	12
- Food Containers (Take out containers) ALL PLASTICITEMS Higher Priority if paper lower priority	13
- Plastic Items (Lamp) ALL PLASTICITEMS Higher Priority	14
- Aerosol Cans Higher Priority	15
Contaminants Not Found In Clips - Loose Diapers Higher Priority	16
- Glass Higher Priority	17
- Fabrics	18
- Coffee Pot Coffee Pods	19
- Lids (Can, bottles, etc.) Higher Priority	20
- Butane Cylinders Uncommon	21

Contaminant Selection worksheet



Final contaminant list

- Compostable bags
- Non-compostable bags
- Yard waste
- Recyclables
- Avoidable food waste



Video Snippets





Annotation





Bounding Boxes



















Preliminary AI Model

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Could recognize 5 items.

Compostable bags: ap = 87.7% (TP = 2131, FP = 1117)

Non- compostable bags: ap = 95.31% (TP = 11367, FP = 2908)

Yard waste: ap = 96.75% (TP = 3370, FP = 707)

Recyclable: ap = 97.33% (TP = 2686, FP = 500)

Avoidable food waste: ap = 85.82% (TP = 674, FP = 268)

Note: ap = average precision

TP = True Positives

FP = False Positives

FN = False Negatives
```



Base AI Model

- Compostable bags: ap = 92.54% (TP = 6662, FP = 2426)
- Non- compostable bags: ap = 95.95% (TP = 19980, FP = 4717)
- Yard waste: ap = 97.5% (TP = 6481, FP = 1235)
- Recyclable: ap = 97.17% (TP = 4584, FP = 864)
- Avoidable food waste: ap = 87.42% (TP = 3436, FP = 1160)

Note: ap = average precision

TP = True Positives

FP = False Positives

FN = **False Negatives**



Model Comparison

Preliminary

TP = 90.25%

FP = 24.45%

FN = 9.7%

Final

$$TP = 90.6\%$$

$$FP = 22.9\%$$

$$FN = 9.37\%$$



Final Model





Real Time Recognition





Conclusions

- It is possible to recognize avoidable food waste and contaminants that are visually different enough and are in view
- Multiple classifications are possible but there needs to be sufficient examples of these classes to get recognition results



Recommendations

- Increase the database size to increase accuracy and number of classes
- Import the model into a mobile hardware platform such as GPS and RFID to link the results to addresses and verify the performance
- Increase frame rate of the camera and supporting hardware to improve the recognition during higher velocity dumping